

I- 1) No friction with air \Rightarrow M.E is conserved (0⁺)

$$M.E_A = M.E_B$$

$$M.E_B = K.E_B + G.P.E_B$$

$$M.E_B = \frac{m_1 V_1^2}{2} = 1.25 \text{ J (1/2)}$$

$$M.E_A = K.E_A + G.P.E_A \Rightarrow$$

$$1.25 = m_1 g L + \frac{m_A V_A^2}{2} (0^+) \Rightarrow$$

$$V_A = 3 \text{ m/s (1/2)}$$

2) L.M is conserved $\Rightarrow \vec{p}_f = \vec{p}_i$

$$m_1 \vec{V}_1 + m_2 \vec{V}_2 = m_1 \vec{V}'_1 + m_2 \vec{V}'_2 \Rightarrow$$

$$m_1 \vec{V}'_1 + 0.4(2 \vec{v}) = 0.1(5\vec{v}) + 0 \Rightarrow$$

$$\vec{V}'_1 = -3 \vec{v} (1/2) \quad (V'_1 \text{ in m/s})$$

$$K.E_f = \frac{m_1 V_1'^2}{2} + \frac{m_2 V_2'^2}{2} = 1.25 \text{ J}$$

$$K.E_i = \frac{m_1 V_1^2}{2} + \frac{m_2 V_2^2}{2} = 1.25 \text{ J}$$

$$K.E_f = K.E_i \Rightarrow \text{Elastic collision (1)}$$

3) $\vec{V}'_1 = -3 \vec{v} \Rightarrow$ Deviation to left (0⁺)

$$M.E \text{ is conserved } M.E_B = M.E_{B'}$$

$$\frac{m_1 V_1'^2}{2} = m_1 g h \Rightarrow$$

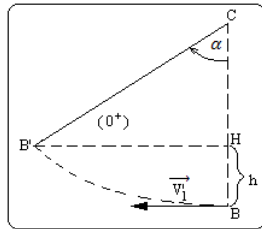
$$h = 0.45 \text{ m (0⁺)}$$

$$h = CB - CH =$$

$$h = L - L \cos \alpha (0^+)$$

$$0.45 = 0.8 - 0.8 \cos \alpha$$

$$\Rightarrow \alpha = 64^\circ (1/2)$$



4) a) $\Delta M.E = W_f \Rightarrow 0 - \frac{m_2 V_2'^2}{2} = -f \cdot d (0^+)$

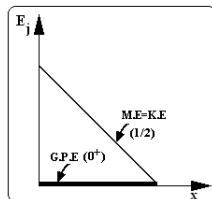
$$f = 0.16 \text{ N (1/2)}$$

b) G.P.E = 0 (0⁺)

$$M.E - M.E_0 = -f \cdot x$$

$$M.E = -0.16x + 0.8 (0^+)$$

$$K.E = M.E (0^+)$$



II-1)

$$M.E = \frac{1}{2} m V^2 + \frac{1}{2} K x^2 = K.E + E.P.E (0^+)$$

$$2) \frac{d(M.E)}{dt} = 0 \Rightarrow x'' + \frac{K}{m} x = 0 (0^+)$$

$$\Rightarrow x'' + \omega_0^2 x = 0 \quad \omega_0 = \sqrt{\frac{K}{m}} (0^+),$$

$$T = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{m}{K}} (0^+)$$

$$3) \omega_0 = \sqrt{\frac{50}{0.5}} = 10 \text{ rd/s (0⁺)}$$

$$x = x_m \sin(\omega_0 t + \varphi)$$

$$\frac{1}{2} m v_0^2 = \frac{1}{2} K x_m^2 \Rightarrow x_m = 0.2 \text{ m (1/2)}$$

$$V = \omega_0 x_m \cos(\omega_0 t + \varphi) \quad V_0 = \omega_0 x_m \cos(\varphi) > 0$$

$$t = 0, x = 0 \Rightarrow 0 = x_m \sin(\varphi) \Rightarrow$$

$$\sin \varphi = 0 \Rightarrow \varphi = 0 \text{ or } \varphi = \pi$$

$$\varphi = 0 \Rightarrow V_0 > 0 \text{ accepted (0⁺)}$$

$$\varphi = \pi \Rightarrow V_0 < 0 \text{ rejected (0⁺)}$$

$$\Rightarrow x = 0.2 \sin(10t) (0^+) \quad (x \text{ in m, } t \text{ in s})$$

4) a) $S = S_0 + \Delta S = S_0 + L \cdot x = S_0 + 0.25x (0^+)$

$$\Phi = B \cdot S \cdot \cos(180^\circ) = -B(S_0 + 0.25x)$$

$$(0^+)$$

$$\Phi = -0.4(S_0 + 0.25x)(0^+)$$

$$b) e = -\frac{d\Phi}{dt} = BLx' = BLV (1/2)$$

$$e_0 = B \cdot L \cdot V_0 = 0.2 \text{ V (1/2)}$$

$$c) I_0 = \frac{e_0}{R} = 0 \quad \text{very large R (1/2)}$$

$$d) \text{ when } R = 5\Omega \Rightarrow I_0 = \frac{0.2}{5} = 0.04 \text{ A (1/2)}$$

The induced current I_0 acts in such a way to oppose the cause producing it \Rightarrow The electromagnetic force \vec{F}_0 is opposite in direction to \vec{V}_0

$$\text{In magnitude: } F_0 = I_0 \cdot B \cdot L \cdot \sin(\widehat{I_0, \vec{B}})$$

$$F_0 = 4 \times 10^{-3} \text{ N (1/2)}$$

The electromagnetic force \vec{F}_{em} acting on MN is opposite to \vec{V} in direction \Rightarrow it damps the oscillations

\Rightarrow the oscillation of MN is damped.

In order to produce S.H.M, we must exert on MN a driving force \vec{F} opposite to \vec{F}_{em} . (0⁺)

The oscillation of MN is called driven oscillation.(0⁺)

III- 1)

$$a) U_{m_1} = 2 \times 3 = 6 \text{ V (0⁺)}, \quad U_{m_2} = 2 \times 1 (0^+)$$

$$U_{m_1} > U_{m_2} \Rightarrow \text{curve } C_1 \text{ represents } u_G (0^+)$$

$$b) U_{m_2} = R \cdot I_m \Rightarrow$$

$$I_m = 0.1 \text{ A (0⁺)}$$

$$\varphi = 2\pi \frac{d}{D} = \frac{\pi}{3} \text{ rd (0⁺)}$$

$$u_G \text{ cuts t-axis before } u_R$$

$$\Rightarrow u_G \text{ leads } i (0^+)$$

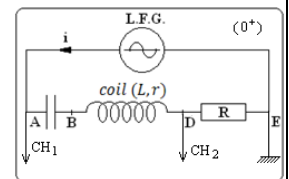
$$T = 6 \times 2 = 12 \text{ mS} = 0.012 \text{ S (0⁺)}$$

$$\omega = \frac{2\pi}{T} = \frac{500\pi}{3} \text{ rd/s (0⁺)}$$

$$u = 6 \sin\left(\frac{500\pi}{3} t\right) (0^+), \quad i = 0.1 \sin\left(\frac{500\pi}{3} t - \frac{\pi}{3}\right) (0^+)$$

$$c) P_{av} = U \cdot I \cdot \cos(\varphi) = 0.15 \text{ W (1/2)}$$

$$P_{av} = (R+r) I^2 \Rightarrow r = 10\Omega (1/2)$$



2)

a) current resonance (0^+) $LC\omega_0^2=1 \Rightarrow L=0.05H$ (1/2)

b) $U_m = (R+r) I_m' \Rightarrow I_m' = 0.2A$ (0^+)
 $i' = 0.2\sin(200\pi t)$ (0^+)

c) $u_C = \frac{q}{C} = \frac{1}{C} \int i. dt = \frac{0.2}{50 \times 10^{-6}} \int \sin(200\pi t)$
 $u_C = -6.28 \cos(200\pi t)$ (0^+)
 $u_{coil} = ri + L \frac{di}{dt} = 2\sin(200\pi t) + 6.28\cos(200\pi t)$
 $u_{coil} = U_{m(r,L)} \sin(\omega t + \varphi') \Rightarrow$
 Calc. $\tan\varphi' = \frac{L\omega}{r} = 3.14 \Rightarrow$
 $\varphi' = 1.26\text{rd} = 72^\circ$ (1/2)
 $U_{m(r,L)} = I_m' \sqrt{r^2 + (L\omega)^2}$
 $u_{coil} = 6.6\sin(200\pi t + 1.26)$ (0^+)

IV-1)

a) $a = \frac{mx + M(0)}{m + M} = \frac{mx}{m + M} = \frac{x}{4}$ (0^+)

b) $I = I_{rod} + I_m = \frac{ML^2}{12} + mx^2 = \frac{1}{20} + 0.2x^2$ (0^+)

c) i) $K.E + G.P.E = M.E = \frac{I\theta'^2}{2} - mgh$ (0^+),
 $h = x \cos \theta$
 $M.E = \frac{I\theta'^2}{2} - 0.2(10)(x \cos \theta) \Rightarrow$
 $M.E = \left(\frac{1}{40} + 0.1x^2\right) \theta'^2 - 2x \cos \theta$
 $M.E = \left(\frac{1}{40} + 0.1x^2\right) \theta'^2 - 2x + x\theta^2$ (1/2)

ii) No friction \Rightarrow M.E is conserved \Rightarrow
 $\frac{dM.E}{dt} = 0$ (0^+), $x = \text{constant} \Rightarrow$
 $\theta'' + \left(\frac{x}{\frac{1}{40} + 0.1x^2}\right) \theta = 0$ (0^+)
 Or $\theta'' + \frac{(M+m).g.a}{I} \theta = 0$
 Similar to $\theta'' + \omega_0^2 \theta = 0$
 $\Rightarrow \omega_0 = \sqrt{\frac{x}{\frac{1}{40} + 0.1x^2}}$ (0^+)
 $T_0 = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{\frac{1}{40} + 0.1x^2}{x}} = 2\pi \sqrt{\frac{1}{40x} + \frac{x}{10}}$ (1/2)

iii) T_0 is min $\Rightarrow \frac{1}{40x} + \frac{x}{10}$ is min \Rightarrow
 $\frac{1}{40x} = \frac{x}{10}$ (using derivative or other method)
 $\Rightarrow x = 0.5\text{m}$ (1/2)
 $T_{0(\text{min})} = 2S$ (0^+), $\pi^2 = 10$

iv) $2.5 = 2\pi \sqrt{\frac{1}{40x} + \frac{x}{10}} \Rightarrow$
 $4x^2 - 6.25x + 1 = 0$ (0^+)
 $\Rightarrow x = 0.16\text{m} < \frac{1}{2}$ (accepted) (1/2)
 $x = 1.38\text{m}$ (rejected) (0^+)

2)

a) $P.E = T.E_{P.E} + G.P.E = \frac{1}{20} C \theta^2 - mg \frac{L}{2} \cos \theta$ (1/2)
 $P.E = \frac{1}{2} C \theta^2 - \cos \theta = \frac{1}{2} C \theta^2 + \frac{1}{2} \theta^2 - 1$
 $P.E = \frac{1}{2} (C + 1) \theta^2 - 1$ (0^+)

b) $M.E = K.E + P.E = \frac{1}{2} I \cdot \theta'^2 + \frac{1}{2} (C + 1) \theta^2 - 1$
 $M.E = \frac{1}{20} \theta'^2 + \frac{1}{2} (1 + C) \theta^2 - 1$ (1/2)
 No friction \Rightarrow M.E is conserved $\Rightarrow \frac{dM.E}{dt} = 0$
 $\Rightarrow \theta'' + 10(1 + C)\theta = 0$ (1/2)
 Similar to $\theta'' + \omega_0^2 \theta = 0$

c) $\Rightarrow \omega_0 = \sqrt{10(1 + C)}$ (0^+)
 $\Rightarrow T_0 = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{1}{10(1 + C)}}$ (1/2)

d) $1.8 = 2\pi \sqrt{\frac{1}{10(1 + C)}} \Rightarrow C = 0.23 \text{ S.I}$ (1/2)

